

# Compression by the signs: distributed learning is a two-way street

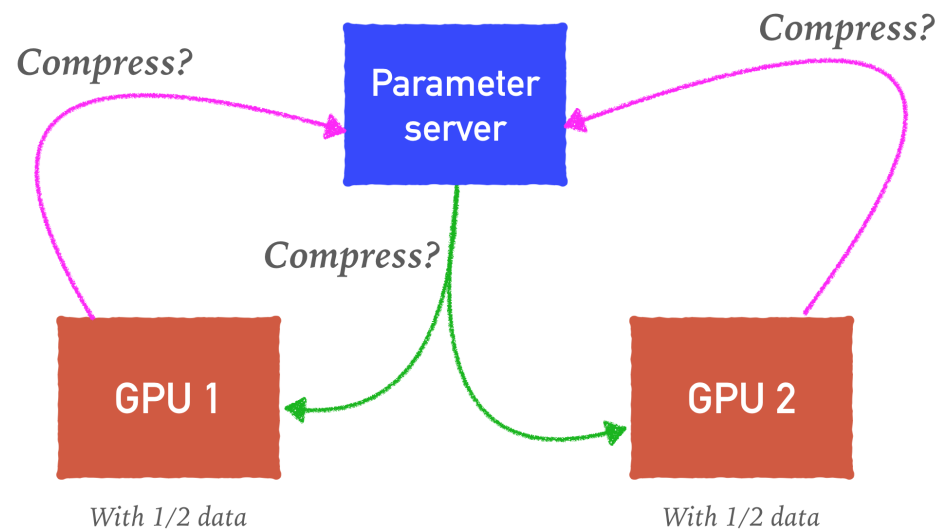
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## Motivation

The sign gradient method performs 1-bit quantisation of gradients, and empirically converges just as fast as SGD for deep networks. Therefore it has potential for **distributed optimisation** where gradient communication across machines is a bottleneck.



Existing gradient quantisation schemes like **QSGD** [1] have good practical performance but weak theoretical foundations. signSGD also resembles **Adam** [2], a popular optimiser which also has weak theoretical foundations.

## signSGD takes the sign of the stochastic gradient

$$x_{k+1} = x_k - \eta_k \text{sign}(g_k)$$

The question is, how can we extend signSGD to the multi-worker setting and still have gradient compression benefits?

We propose signSGD with majority vote. The scheme is elegant since **all communication is 1 bit quantised**.

## Majority vote lets $M$ workers vote on the true gradient sign

$$x_{k+1} = x_k - \eta_k \text{sign} \left[ \sum_{i=1}^M \text{sign}(g_k) \right]$$

- 1 each worker sends its stochastic sign gradient to the parameter server
- 2 the parameter server sums the independent estimates and returns the majority decision

## Single worker theory

The first step is to establish the properties of the single worker algorithm, which is just signSGD.

We work in the non-convex setting, under very general assumptions.

### Assumptions

- 1 Objective function has a lower bound  $f^*$
- 2 Objective function has coordinate-wise Lipschitz smoothness  $\vec{L}$
- 3 Stochastic gradient has a coordinate-wise variance bound  $\vec{\sigma}$

We prove the convergence rate of signSGD to first order critical points (either saddles or local minima).

### Convergence rate for single-worker signSGD

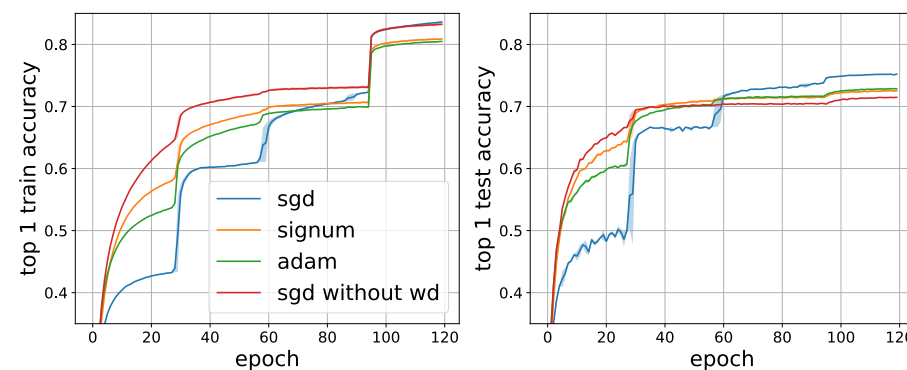
$$\mathbb{E} \left[ \min_{0 \leq k \leq K-1} \|g_k\|_1 \right]^2 \leq \frac{1}{\sqrt{N}} \left[ \sqrt{\|\vec{L}\|_1} \left( f_0 - f_* + \frac{1}{2} \right) + 2\|\vec{\sigma}\|_1 \right]^2$$

## Comparing the rate to SGD

- 1  $N$  measures the number of stochastic gradient calls up to step  $K$
- 2 the  $1/\sqrt{N}$  rate matches SGD
- 3  $\ell_1$  norms replace the typical SGD-style  $\ell_2$  norms
- 4 the theory relies on a large batch size which has systems benefits

## Single worker performance on Imagenet

We find that signSGD has **extremely similar Imagenet performance to Adam**.



signSGD performs slightly worse than SGD, but this may be because we used a much smaller batch size than suggested by theory.

## Multi worker theory

Remarkably we are able to show that signSGD with majority vote gets the **same theoretical speedup as full-precision distributed SGD**.

The result holds under one additional assumption:

### Assumptions

- 1 Objective function has a lower bound  $f^*$
- 2 Objective function has coordinate-wise Lipschitz smoothness  $\vec{L}$
- 3 Stochastic gradient has a coordinate-wise variance bound  $\vec{\sigma}$
- 4 **Stochastic gradient noise is symmetric about the mean**

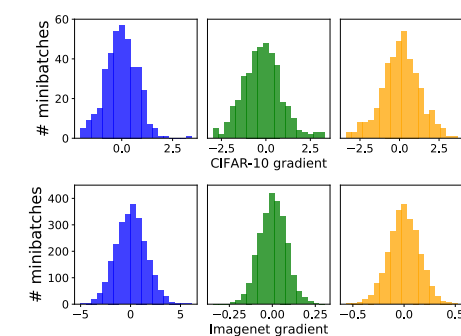
This additional assumption is reasonable by the central limit theorem.

### Convergence rate for $M$ -worker majority vote

$$\mathbb{E} \left[ \min_{0 \leq k \leq K-1} \|g_k\|_1 \right]^2 \leq \frac{1}{\sqrt{N}} \left[ \sqrt{\|\vec{L}\|_1} \left( f_0 - f_* + \frac{1}{2} \right) + \frac{2}{\sqrt{M}} \|\vec{\sigma}\|_1 \right]^2$$

## Validating the additional assumption

We plot stochastic gradient histograms for 6 randomly chosen neural network weights. We find that **gradient noise in real problems is approximately symmetric**, even for mini-batches of size  $O(100)$ .



## Next steps

- 1 single worker signSGD is available in mxnet now!
- 2 we are currently implementing and testing majority vote

## Bibliography

- [1] Dan Alistarh et al. QSGD. 2017
- [2] Diederik P. Kingma, Jimmy Ba. Adam: A Method for Stochastic Optimization. 2014